General Version 1.1

H-250(G)-12V is one of the smallest CO2 sensor modules in the world which measures high concentration CO2 ranges (0~25%). Its Persistent Stability and Temperature Effect Resistance besides easy management are much favored by customers in CA Storage, Greenhouse, scientific projects, etc.

# ELT Sensor Data Sheet for H-250(G)-12V



#### **Features**

- Non-Dispersive Infrared (NDIR) technology used to measure CO<sub>2</sub> levels.
- · Pre-calibrated
- Available outputs : TTL-UART, I2C, Alarm

(PWM / Analog Voltage : option)

- Gold-plated sensor provides long-term calibration stability.
- Installed re-calibration function
- Non-Periodic Manual Re-Calibration (MCDL) are available. (Calibration with 0ppm or 400ppm CO2 gas)

• Size: 50mmx69mmx20mm

• Weight : 20 grams

# H-250(G)-12V Specifications

#### **General Performance**

Operating Temperature : -10 ~ 60 °C

**Operating Humidity :** 0 ~ 95% RH (Non-condensing) , 'G' option : 0 ~ 99% RH (Non-condensing)

**Operating Environment :** Incubators, CA Storages, Industry fields etc.

Storage Temperature : -30 °C ~70 °C

# CO<sub>2</sub> Measurement

Sensing Method: NDIR (Non-dispersive Infrared)

**Measurement Range :**  $0 \sim 25\% (0 \sim 5\%/10\%/15\%/20\% \text{ models are available})$ 

Accuracy:  $\pm$ (300ppm+3%) of reading (1)(2)

Step Response Time (T90): 2 minutes

Sampling Interval: 3 seconds

**Warming-up Time :** < 6 seconds (for Operation), 5 minutes (for Accuracy)

#### **Electrical Data**

**Power Input**: 12V± 5% (3)

Connectors: 4pin B-to-B con. or 13pin Side hole

Current Consumption: Normal mode: 27mA, Peak < 374mA

### **Product Derivatives and Relative Functions**

Products	Option List
H-250-12V	UART,I2C, ALARM. (Analog Voltage or PWM is optional), 0_MCDL, 400_MCDL
H-250 <b>G</b> -12V	Resistance up to 99% Humidity for Application of Green House

H-250(G)-12V has various output TTL-UART, I2C and ALARM while as PWM / AVO is selectable as option. 2.54pitch 13pin side holes and 2mm pitch 10 and 4pin 2 row header connector are available. Manual Calibration (10' MCDL) are executable by sending 'Low Signal' to pin-11 and pin-13 of J13.

<sup>(1)</sup> Periodical MCDL is recommended to keep accuracy.

<sup>(2)</sup> Air pressure is assumed as 101.3 kPa

<sup>(3)</sup> DC Supply should be regulated, low noise power source for best accuracy

# Pin Map with J1&J2 Connectors

J-1	Description
1	(+12V VCC)
2	TXD
3	GND

J-2	H-250(G)-12V	H-250(G)-12V (PWM Option)									
1	(+5V	(+5V VCC)									
2	T>	TXD									
3	R	RXD									
4	GN	GND									
5	/PS	/PSEN									
6	/RESET										
7	Analog Voltage Output (2~10V) PWM										

# Pin Map with J3 Connectors (Side Hole)

J-3	H-250(G)-12V	H-250(G)-12V (PWM Option)								
1	CAL 1: CO2 400 ppm Manual Calibration (400_MCDL, 10 min)									
2	/PS	/PSEN								
3	CAL 2: CO2 0 ppm Manual C	Calibration (0_MCDL, 10 min.)								
4	/RE	SET								
5	I2C	SDA								
6	I2C	I2C SCL								
7	Reserved PWM option									
8	RXD									
9	TXD									
10	V	CC								
11	GND									
12	-									
13	Analog Voltage Output (2~10V) Reserved									

# Pin Map with J4 Connectors (Side Hole)

J-4	H-250(G)-12∨	H-250(G)-12V
1	Rese	rved
2	GN	ID
3	GN	ID

# Pin Map with J5 Connectors (Side Hole)

J-5	H-250(G)-12V	H-250(G)-12V							
1	CAL 1: CO2 400 ppm Manual Calibration (400_MCDL, 10 min)								
2	CAL 2: CO2 0 ppm Manual Calibration (0_MCDL, 10 min.)								
3	N (Normal)								

**UART** (J-12:P1&P2): 38,400BPS, 8bit, No parity, 1 stop bit

**I2C** (J-12:P3&P4) : Slave mode only, Internal pull up resister (10kΩ) TTL Level Voltage :  $0 \le V_{IL} \le 0.8$ ,  $2 \le V_{IH} \le VDD$ ,  $0 \le V_{OL} \le 0.4$ ,  $2.4 \le V_{OH} \le VDD$  (Volt)

# **ALARM** (Open Collector type)

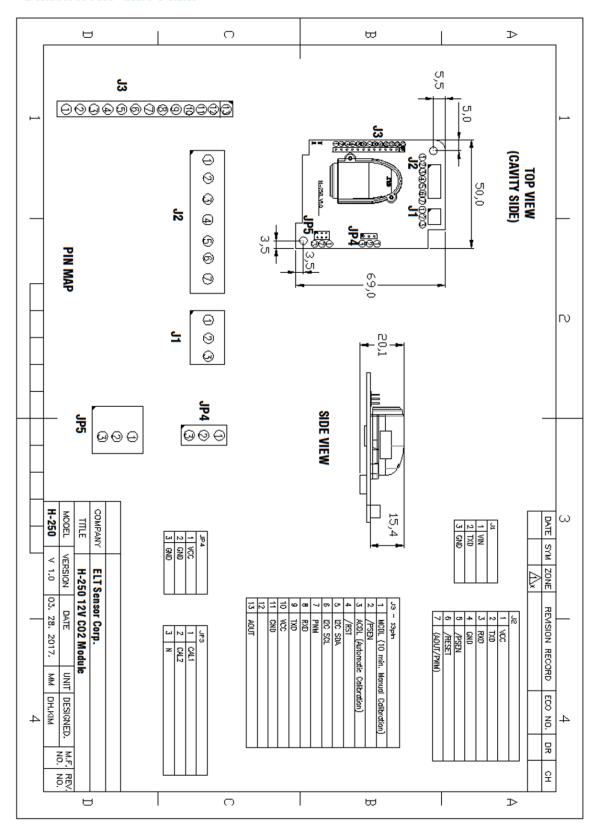
10,000 ppm ≤ Alarm ON, 8,000 ppm ≥ Alarm OFF and alarming range can be change by EK-100SL with connected to PC.

Option 1: Analog Voltage(J-2:pin-7, J-3:pin-13): 2~10 V.

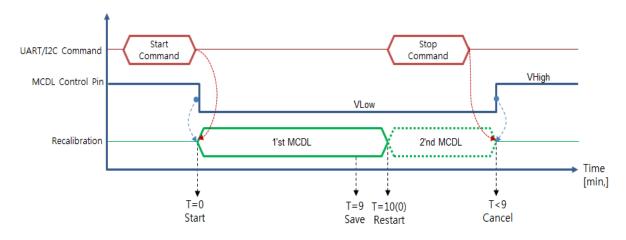
Option 2: PWM (J-2, J-3: pin-7 is available) In case the PWM option is chosen,

 $t_H$  = 2 msec (Start) + 1,000 msec x (Measurement<sub>(ppm)</sub> / Range<sub>(ppm)</sub>),  $T_L$  = 2,000 ms -  $t_H$ 

# Dimensions unit: mm



# 10' MCDL function (10 minute Manual Calibration Function in Dimming light)



Time Diagram of MCDL

Method 1. UART Command Set; J12: pin-1 (UART-RX) and pin-2 (UART-TX) to Main-Board. (J13: pin-6 and pin-5 are available as well)

I2C Command Set; J12: pin-3 (SCL) and pin-4 (SDA) to Main-Board.

(J13: pin-8 and pin-9 are available as well)

Method 2. For PWM or AVO (Analog Voltage Output), Hardware based MCDL setting is available.

Status	0_MCDL (J3:3or J5:2)	400_MCDL (J3:1or J5:1)	Notes
CAL 1 (H/W 0_MCDL)	Low	High	Sensor should be located in Oppm environment (outside) for 10 minutes
CAL 2 (H/W 400_MCDL)	High	Low	Sensor should be located in 400ppm environment (outside) for 10 minutes
None	High	High	Factory Calibration Status or Last Calibrated Status

<sup>\* 1. (</sup>J3:pin-1 or J3:pin-3) and (J5:pin-1 or J5:pin-2) shouldn't have 'Low' at any time.

Method 3. Let Sensor install on Jig Board, **TRB-100ST (Test and Recalibration Board)** with ambient air-flow condition and execute by moving jumper following Manual on the website.

<sup>2.</sup> Be sure to quit MCDL fetch loop before 18minute.

Method 4. **EK-100SL (Evaluation kit, with Emulation program 'ELTWSD')** is available, which display and save data on PC through USB connection.

### \* Set present CO2 value with Target PPM function

- 1. Deviated CO2 sensors can be adjusted with target PPM function via I2C or UART interface. (Refer to 'I2C Programming guide' or 'UART Command guide')
- 2. EK-100SL (Evaluation kit, with Emulation program 'ELTWSD') is available for Target PPM function. (Refer to 'EK-100SL manual')

# **Output Descriptions**

\* UART : Output unit of measured value is PPM or Percent(%).

I2C: Output unit of measured value is PPM or Percent(%).

But, I2C gives the data as below;

PPM = Measured value x 100, Percent(%)= Measured value / 100

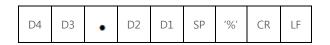
### **UART Descriptions**

#### **Data Transmit**

Interval: 3 seconds, Handshake protocol: None (Data is transmitted to outer device periodically)

### **Data Format**

### 1. % (percent)



D4 D3 • D2 D1	CO2 density string				
SP	Space: 0x20				
'%'	'%' : 0x25				
CR	Carriage return : 0x0D				
LF	Line feed : 0x0A				

Above 9 byte consist by 5 byte hexadecimal digits, <SP>,0x25, <CR><LF> , where decimal '0' (corresponds to hexadecimal digit '0x30') is replaced by space (corresponds to hexadecimal digit '0x20') for lower value than 10%.

EX) 0.08%, results in '0x30 0x2E 0x30 0x38 0x20 0x25 0x0D 0x0A', which displays '0.08\_%<CR><LF>'on screen. 5% corresponds '0x35 0x2E 0x30 0x30 0x20 0x25 0x0D 0x0A', which displays '5.00\_%<CR><LF>', 15% gives '0x31 0x35 0x2E 0x30 0x30 0x20 0x25 0x0D 0x0A', which displays '15.00\_%<CR><LF>'.

### 2. ppm (part per million)

D6	D5	D4	D3	D2	D1	SP	'p'	'p'	'm'	CR	LF
		D6	~ D1		6 1	ovto (	-O2 c	loncity	, ctrin	a	
			SP DI			6 byte CO2 density string  Space: 0x20					
			om′						string		
			ir R						turn :		
		L	.F			Lin	e fee	d : 0x0	)A		

Above 12byte consist by 6 byte hexadecimal digits, <SP>,0x70 0x70 0x6D, <CR><LF>, where decimal '0' (corresponds to hexadecimal digit '0x30') is replaced by space (corresponds to hexadecimal digit '0x20'),

EX) 1,255 ppm, results '0x20 0x20 0x31 0x32 0x35 0x35 0x20 0x70 0x70 0x6D 0x0D 0x0A', which displays '\_\_1255\_ppm<CR><LF>'on screen.

# **I2C Communication (Only Slave Mode Operation)**

Internal pull up resister

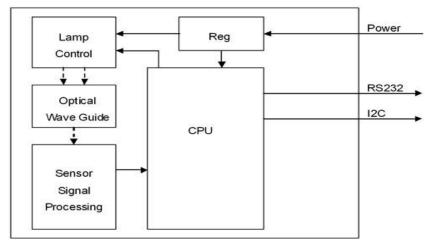
Slave Address: 0x31, Slave Address Byte: Slave Address(0x31) 7 Bit + R/W 1 Bit

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0	1	1	0	0	0	1	R/W Bit

R/W Bit : Read = 1/Write = 0

When reading the data, Slave Address Byte is 0x63, When writing the data, Slave Address Byte is 0x62.

#### **Block Diagram**



# **Transmission Sequence in Master**

- 1) I2C Start Condition
- 2) Write Command(Slave Address + R/W Bit(0) = 0x62) Transmission and Check Acknowledge
- 3) Write Command(ASCII 'R': 0x52) Transmission and Check Acknowledge
- 4) I2C Stop Command
- 5) I2C Start Command
- 6) Read Command(Slave Address + R/W Bit(1) = 0x63) Transmission and Check Acknowledge
- 7) Read 7 Byte Receiving Data from Module and Send Acknowledge (Delay at least 1ms for reading each byte)

Со	nfigura	ation		C	O <sub>2</sub>		reser	ved	Re	eserved	reserved			reserved
	1 Byte 2 Byte					0x0	00		0x00		0x00		0x00	
													•	
0	0	0	0	1	0	0	0							

Sensors give 1/100 ppm of measurement which correspond to 100 times of percent.

For % (percent) output, the measured value should be used after division by 100.

EX) if measured value is 1,250, it is 12.5% (1,250/100 = 12.5%).

For ppm output, the measured value should be used after multiplication by 100.

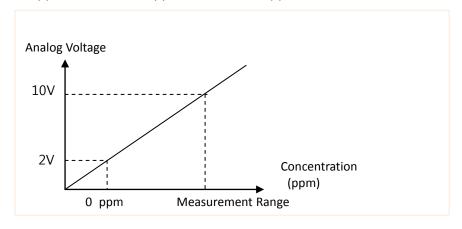
EX) if measured value is 1,250, it is 125,000ppm (1,250\*100 = 125,000ppm).

In need of detail protocol specification and time sequence, I2C programming guide is capable of providing through Sales Rep.

# **Analog Voltage Description; Option**

\* Measurement<sub>(% or ppm)</sub> : 2~10V

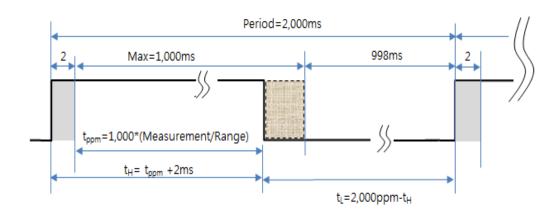
Measured Voltage  $2V\sim10V$  matches proportionally to  $0\sim5\%(50,000ppm)$ , 10%(100,000ppm), 15%(150,000ppm), 20%(200,000ppm), 25%(250,000ppm)



\* CO2 Measurement (%) = ((Output  $_{Voltage}$  - 2)/ (10 - 2)  $_{Voltage}$  )x F.S. %, cf. F.S. % : 5% / 10% / 15% / 20% / 25% EX) if the Output  $_{Voltage}$  is 5V in 20% (F.S. of Reading range) CO2 Measurement(%) = (5 - 2) V ÷ (10 - 2) V x 20% = (3 ÷ 8) x 20% = 7.5%

\* CO2 Measurement (ppm) = ((Output  $_{Voltage}$  - 2)/ (10 - 2)  $_{Voltage}$ )x F.S. (ppm), cf. F.S. (ppm) : 50,000 / 100,000 / 150,000 / 200,000 / 250,000 ppm EX) if the Output  $_{Voltage}$  is 5V in 200,000 ppm (F.S. of Reading range) CO2 Measurement ppm = (5 - 2) V ÷ (10 - 2) V x 200,000 ppm = (3 ÷ 8) x 200,000 ppm = 75,000 ppm

# **PWM Descriptions ; Option**



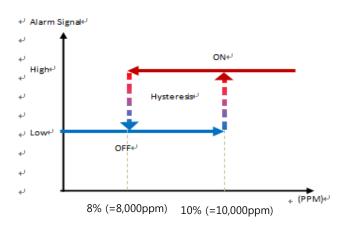
- \* Measurement<sub>(ppm) =</sub>  $(t_H-2msec)/1000msec x Range_{(ppm)} (t_H : High Pulse Width)$
- \* Range<sub>(ppm)</sub>: 2,000/3,000/5,000/10,000 ppm (20,000/30,000/50,000/100,000 is optional.)

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EX) t_H (High Pulse Width) calculation for 5% in 10% Reading range. 
*Measurement<sub>(ppm)</sub> = 5% = (t_H-2ms)/2,000msec x Reading range<sub>(ppm)</sub> , 
*t_H= 2,000 msec * (5% / 10%) + 2msec = 1,002msec 
(cf: T_L= Period - t_H = 2,000 ppm - 1,002 msec = 998 msec.) 
EX) t_H (High Pulse Width) calculation for 4,000 ppm in 50,000 ppm Range. 
*Measurement<sub>(ppm)</sub> = 4,000 ppm = (t_H-2ms)/2,000msec x Range<sub>(ppm)</sub> , 
*t_H= 2,000 msec * (4,000 ppm / 50,000 ppm) + 2msec = 162msec 
(cf: t_L= Period - t_H = 2,000 ppm - 162 msec = 1,840 msec.)
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# **Alarm Descriptions**

Alarm is Open Collector type which work SPST (Single Pole Single Throw). Alarm is 'OFF' status at first and turn to 'ON' status since CO2 value go beyond 10,000ppm until it go down to 8,000ppm to avoid unwanted rapid switching by hysteresis effect.





EK-100SL series is available for customer to enable to change alarm activation & deactivation point.

# **X** Caution

- 1. Please hold only 'PCB' of sensor without holding Cavity directly to avoid the physical shock on sensor. Rough handling or Transportation could result in inaccurate reading.
- 2. Proper ESD protection during handling is important to avoid electrostatic defect occurrence. The storage of sensor should be insulated as well.

**X** Specification of H-250 Series could be changed without notice.

#### ELT SENSOR Corp.